

# Pixelink®

A NANITAR COMPANY

## PL-D753

### CMOS | SONY IMX421 | HDR MODEL

The Pixelink PL-D753 camera model with the Sony IMX421 3rd generation Pregius CMOS global shutter sensor is ideal for high dynamic range imaging applications requiring both high resolution images and fast frame rates. Available in mono and color, the IMX421 performs well in the NIR range.

HDR imaging is a technique used to render a captured image with a greater dynamic range of luminosity than is possible with standard digital imaging. A key feature of the IMX421 Sony sensor is a Dual ADC mode where each pixel can be read out with two different gains when enabled.

The PL-D753 combines the Dual ADC images into a single hybrid HDR image, directly on camera - thus removing the need for any host processing. Real time on camera HDR is an easy way for the user to gain 6-10dB of additional dynamic range on their image without straining the CPU or requiring additional complex software algorithms.

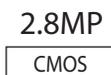
As with all the Pixelink cameras, the PL-D753 is compatible with Pixelink Capture, our free real-time interactive multi-camera software application.



### TYPICAL APPLICATIONS

- High Speed Inspection
- Security
- Real-time Sports Analysis
- Medical Imaging
- PCB Inspection

### KEY FEATURES



## TECHNICAL SPECIFICATIONS

### SENSOR

Sensor	Sony IMX421
Type	CMOS Global Shutter
Resolution	2.8MP (1936 x 1464)
Pixel Pitch	4.5 µm x 4.5 µm
Active Area	11 mm diagonal

### PERFORMANCE SPECIFICATIONS

FPN	< 0.03% of signal
PRNU	< 0.4% of signal
Dynamic Range	72 dB
Bit Depth	8 or 12-bit
Color Data Formats	Bayer 8, Bayer 12 Packed, Bayer 16 & YUV422
Mono Data Formats	Mono 8, Mono 12 Packed & Mono 16

### FRAME RATES

Resolution	Free Running
1936 x 1464	141.1 fps
1280 x 1024	203 fps
640 x 480	403.8 fps
Frame rates will vary based on host system and configuration	
*Above calculations based on fixed frame rate mode	

### INTERFACES

Interface   Data rate	USB 3.0   Micro-B   5Gbps
Board Level Trigger Connector	8-pin Molex 1.25mm pitch
Enclosed Trigger Connector	Hirose round 8-pin
Trigger	Software and hardware
Board Level Trigger Input	1 input, 3.3V (with internal pullup resistor)
Enclosed Trigger Input	1 optically isolated, 5-12V DC at 4-11 mA
Board Level GPO/Strobe	2 outputs, 3.3V
Enclosed GPO/Strobe	2 outputs, 3.3V and 1 optically isolated max 40V DC, max 15mA
GPI	1 input, 3.3V (with internal pullup resistor)

### MECHANICALS

Dimensions (mm)	55 x 38.5 x 30.29
Weight (g)	35.8 (Board level without optics)
Mounting	C-Mount

### POWER REQUIREMENTS

Voltage Required	5V DC (from USB connector)
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### PIN NAME & FUNCTION

1	3.3V power output
2	TRIGGER/GPI 3.3V HCMOS input
3	Ground
4	GPO1, 3.3V HCMOS output
5	GPO2, 3.3V HCMOS output
6	Clock, 3.3V (I2C access for OEMs)
7	Data, 3.3V (I2C access for OEMs)
8	No connection
Board connector: Molex (8-pin, 1.25mm pitch, vertical); Cable receptacle: Molex 51021-0800; Cable crimp terminals: Molex 50079-8100	

### ENCLOSED GPIO INTERFACE PIN OUTPUT DESCRIPTION

1	VBUS (Power output from USB 3.0 cable)
2	TRIGGER + (optically isolated)
3	TRIGGER - (optically isolated)
4	GPO1 + (optically isolated)
5	GPO1 - (optically isolated)
6	GPO1, 3.3V HCMOS output (I2C - SCL for autofocus)
7	GPO2, 3.3V HCMOS output (I2C - SDA for autofocus)
8	Ground (logic and chassis ground)

### ENVIRONMENTAL & REGULATORY

Compliance	FCC, CE & RoHS
Shock & Vibration	300 G & 20 G (10Hz - 2KHz)
Operating Temperature	0°C to 50°C
Storage Temperature	-45°C to 85°C

### SOFTWARE

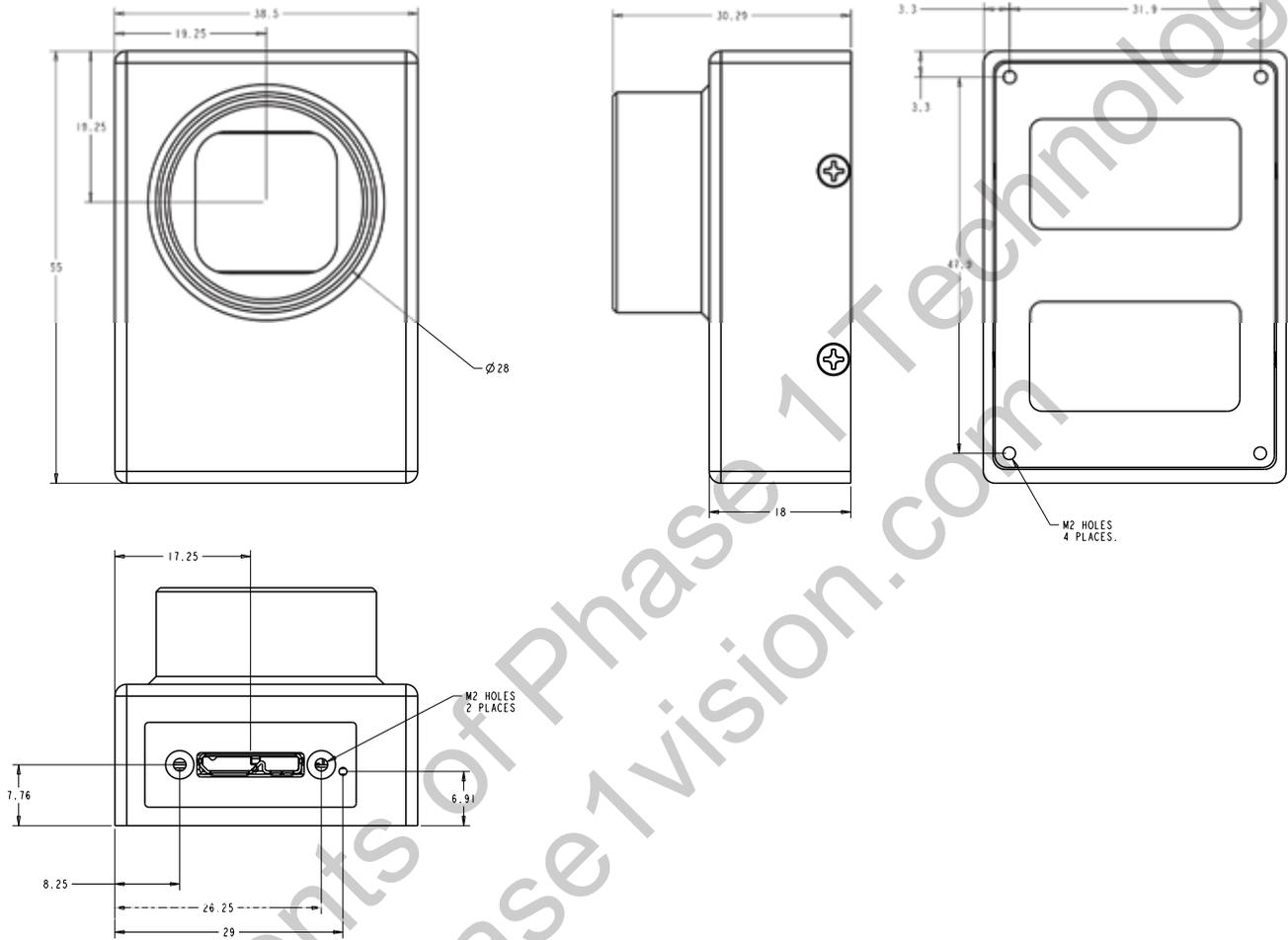
Pixelink Capture	Control & operate multi-camera
Pixelink SDK	Software Development Kit
Pixelink µScope	Acquisition, analysis & reporting
3rd. Party U3V Vision Applications	

### COMPUTER & OPERATING SYSTEM

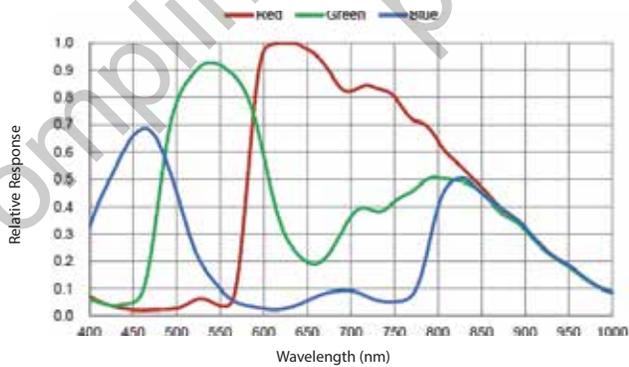
	Windows	Linux x86	Linux ArmV7	Linux ArmV8
Processor	Intel i5 or better	Intel i5 or better	Arm7 (32 bit)	Arm8 (64 bit)
Memory	4GB recommended	4GB recommended	2GB	2GB
Hard Drive Space	150 MB	150 MB	50 MB	50 MB
Operating System	Windows 7/8/10	Ubuntu 14.04/16.04 Desktop	Ubuntu 14.04/16.04	Ubuntu 14.04/16.04

# MECHANICAL DRAWINGS & RESPONSIVITY CURVES

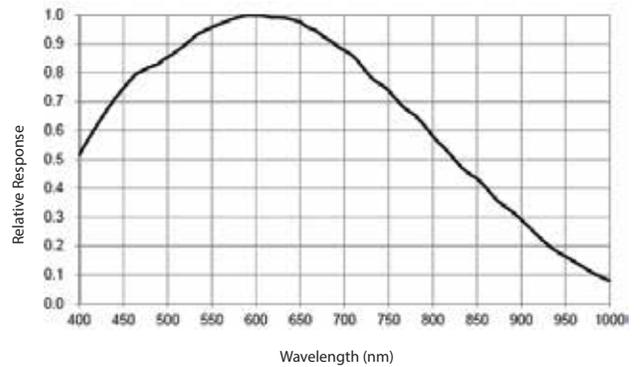
## MECHANICAL DRAWINGS



## RESPONSIVITY CURVE - COLOR



## RESPONSIVITY CURVE - MONO



## PIXELINK'S INDUSTRY LEADING SOFTWARE

### PIXELINK CAPTURE

Pixelink Capture is powerful multi-camera software application designed to configure "n" numbers of cameras and stream "n" number of cameras simultaneously in real-time high-quality video viewed in a multi-window environment. Pixelink Capture offers options for complex image enhancements such as; exposure control, filtering, frame-by-frame property changes in addition to multi-camera application testing and configuration.

Pixelink Capture also provides features to measure supporting; point, line, circle, rectangle, polyline and polygon measurements while determining pixel location. After creating spatial calibration, the user can review and adjust before exporting the findings to an Excel spreadsheet for further analysis. Pixelink Capture also has integrated lens control (zoom & focus) for Navitar motorized lenses and accurate autofocus options for Navitar motorized fine focus mechanisms.

Visit [pixelink.com](http://pixelink.com) for more detailed information.

### PIXELINK SDK

Providing full control of all camera functions, the Pixelink Software Developers Kit (SDK) is the software package of choice for developers and system integrators who are integrating Pixelink cameras into their applications. The Pixelink SDK provides access to the full Pixelink Application Programming Interface (API) and provides sample applications, wrappers for many 3rd party controls, such as LabVIEW, along with full documentation.

The Pixelink SDK is compatible with Microsoft Windows and popular Linux platforms. When using the Pixelink SDK, developers can integrate Pixelink cameras into their custom applications with ease.

## AVAILABLE CONFIGURATIONS

PL-D753CU  
PL-D753CU-BL  
PL-D753CU-T

PL-D753MU  
PL-D753MU-BL  
PL-D753MU-T

Color Space  
C = Color  
M = Mono  
NIR = Near Infrared

Interface  
F = Firewire  
G = GigE  
U = USB

Housing  
CS = CS Mount  
S-BL = S Mount Board Level  
BL = Board Level  
T = Trigger