

English

VISION:mini™

29mm cubic VGA High-Speed B/W CMOS Camera

VCC-GC20V41CL

Product Specification & Operational Manual

CIS Corporation

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1. Scope of Application

This is to describe VCC-GC20V41CL, high-speed B/W CMOS Camera. All specifications contained herein are subject to change without prior notice. Reproduction in whole or in part is prohibited.

2. Handling Precautions

The camera must not be used for any nuclear equipments or aerospace equipments with which mechanical failure or malfunction could result in serious bodily injury or loss of human life. Our warranty does not apply to damages or defects caused by irregular and/or abnormal use of the product.

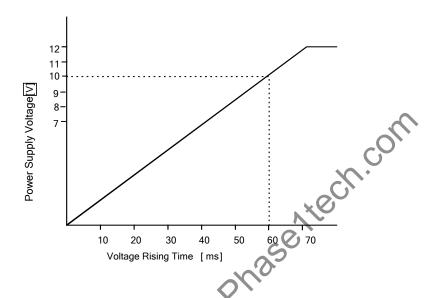
Please observe all warnings and cautions stated below.

Our warranty does not apply to damages or malfunctions caused by neglecting these precautions.

- Do not use or store the camera in the following extreme conditions:
 - Extremely dusty or humid places.
 - ➤ Extremely hot or cold places (operating temperature -5° to +45°C)
 - > Close to generators of powerful electromagnetic radiation such as radio or TV transmitters.
 - Places subject to fluorescent light reflections
 - > Places subject to unstable (flickering, etc.) lighting conditions.
 - Places subject to strong vibration.
- Remove dust or dirt on the surface of the lens with a blower.
- Do not apply excessive force or static electricity that could damage the camera.
- Do not shoot direct images that are extremely bright (e.g., light source, sun, etc.), and when camera is not in use, put the lens cap on.
- Follow the instructions typeapter 7, "External connector pin assignment" for connecting the camera. Improper connection may cause damages not only to the camera but also to the connected devices.
- Confirm the mutual ground potential carefully and then connect the camera to monitors or computers. AC leaks from the connected devices may cause damages or destroy the camera.
- Do not apply excessive voltage. (Use only the specified voltage.) Unstable or improper power supply voltage may cause damages or malfunction of the camera.

 The voltage ripple of camera power DC +12V±10% shall be within ±50mV. Improper power supply voltage may cause noises on the video signals.

• The rising time of camera power supply voltage shall be less than +10V, Max 60ms. Please avoid noises like chattering when rising.



In case of abnormal operation, contact the distributor from whom you purchased the product.

3. Notes on Partial Scan Mode Operation

At vertical partial scan mode, the smaller the set reading out lines, the faster the camera exposure and output operation will be. And, at the same time, power consumption will be increased.

Power consumption when the minimum partial scan line number is set will be approx. 2.4W, while it will be approx. 1.6W at full frame scan. That is about 1.5 times higher. With higher power consumption, heat will be increased as well.

We recommend promoting heat dissipation when installing our camera to your system, especially when reading out line is set between the ranges of 50lines to 1line.

For instance, installing the camera to the place under 40 degrees C ambient temperature, or installing the camera to a metalic part, would be effective.

4. Product Outline

VCC-GC20V41CL is an industrial B/W high-speed digital video camera module utilizing a global shutter type, CMOS sensor. Interface of GC20V41CL complies with camera link (Base Configuration) with its resolution 300K pixels. Clipping part of the image for VGA 1/4 type size, entire pixels can be read out within approx. 1/500s.

key Features	, V '
☐ High frame rate, 502.29	fps, at full frame scan mode with Camera Link Base Configuration.
Frame rate = (pixel	clock) / (((horizontal output pixels/output tap number)
+ Horizontal Blankir	ng) × (Vertical Output Lines + Vertical Blanking))
= (79.99MHz) / (((6	40/2) +5)×(480+10))
= 502.29fps	
W.	
☐ 29mm cubic in size (exclu	uding projection).
☐ Camera Link 2Tap output	t (Base Configuration)
☐ 8bit / 10bit selectable	
☐ External Trigger	
☐ Shutter Speed: 1/500s ~	~1/50,000s
☐ Fixed Trigger Shutter Mo	de
☐ Pulse Width Trigger Shut	ter Mode
☐ Partial Scan Mode (Vertic	al)
☐ Free sample control softw	ware for evaluation purpose only is downloadable via our web.

5. Specification

5.1. General Specification

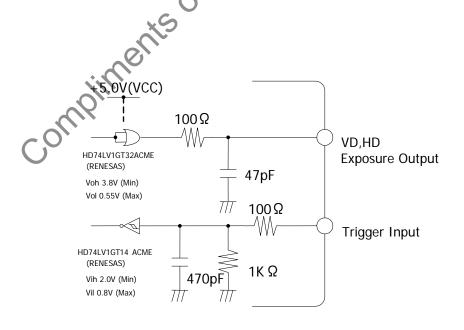
	1tem	Specification						
		Device Type	B/W CMOS					
		Effective Pixel Number	640(H) × 480(V)					
		Unit Cell Size	$5.50 \mu\text{m}(\text{H}) \times 5.50 \mu\text{m}(\text{V})$					
(4)		Chip Size	$3.52\text{mm}(H) \times 2.64\text{mm}(V) (640 \times 5.5 \mu\text{m}(H) \times 480 \times 5.5 \mu\text{m}(V)$					
(1)	Pickup Device	Image Circle	φ 4.4mm 2.64 (Unit: mm)					
		Pixel Clock	79.99 MHz					
		Horizontal Frequency	246.12kHz Pixel Clock: 325CLK					
(2)	Video output frequency	Vertical Frequency	Full Frame Scan Mode: 502 29Hz Scanning Lines: 490H					
			Partial Scan Mode 984.49Hz Scanning Lines: 250H					
			(Vertical 1/2):					
(3)	Sync. system	Internal Sync. System						
(4)	Video output standard	Camera Link 2Tap Output (Base Configuration)						
(5)	Resolution	480 TV lines equivalent (VGA size)						
(6)	Output Format	8bit/10bit selectable						
(7)	Sensitivity	F2.0 400lx (Shutter Spe	ed: 1/500s Gain 0dB)					
(8)	Minimum illumination	F1.4 5.0lx (Shutter Spee	ed: 1/500s, Gain +12dB)					
(9)	Dust or stains in	No dust or stain shall be detected on the testing screen with setting the camera aperture at F16.						
	optical system							
(10)	Power requirements		ge shall not be exceeded +15V.)					
(11)	Power consumption	Approx. 1.6W at ful frame						
		Approx. 2.4W at partial so	can with minimum line number setting (DC DC+12V IN).					
(12)	Dimension	Refer to overall dimension H:29mm W:29mm D:	n drawing (Clause 12) 29mm (excluding projection)					
(13)	Mass	Approx. 50g						
(14)	Lens mount	C mount (Refer to overa	ıll dimension drawing)					
	Optical axis accuracy		S Optical Axis Accuracy (Clause 11)					
(16)	Gain variable range	0~+12dB (Digital Gain:+0.1dB/step)						
(17)	Gamma	1(Fixed)						
(18)	Shutter speed	OFF(1/500),1/750s,1/100	0s,1/1500s,1/2000s,1/2500s,1/4000s,1/5000s,1/10000s,1/15000s,					
	variable range	1/20000s,1/25000s,1/300	000s,1/40000s,1/50000s					
(10)	Trigger shutter mode	 Fixed Trigger Shutter Mo 	ode					
(17)	mygor shatter mode	 Pulse Width Trigger Shut 	tter Mode (Exposure time is set with the pulse width of trigger signal.)					

Item		Specification					
	UL:	Conform to UL Standard including materials and others.					
	CE:	Conform to EN55022:2006 (Class B) for Emmission					
	RoHS:	Conform to RoHS					
(20) Safety/Quality standards		To be applied for FCC Class A Digital Device					
		This device complies with Part 15 of FCC Rules. Operation is subject to the					
	FCC:	followiong two conditions: (1) this device may not cause harmful interference, and					
		(2) this device must accept any interference received, including interference that					
	UL: Conform to UL Standard including materials and others. CE: Conform to EN55022:2006 (Class B) for Emmission Conform to EN61000-6:2005 for Immunity RoHS: Conform to RoHS To be applied for FCC Class A Digital Device This device complies with Part 15 of FCC Rules. Operation is subject to followiong two conditions: (1) this device may not cause harmful interference (2) this device must accept any interference received, including interference may cause undesired operation. Acceleration: 98m/s² (10G) Frequency: 20~200 Hz Direction: X,Y,Z 3 directions Testing time: 120 min for each direction No malfunction shall be occurred with 980m/s² (100G) for ±X, ±Y, and ± directions. (without package) Operation guaranteed: -5°C~+45°C Performance guaranteed: 0°C~+40°C Humidity RH 20~80% with no condensation						
		Acceleration : 98m/s ² (10G)					
		Frequency : 20~200 Hz					
	Vibration						
(21) Durability							
		Ÿ					
	Shock						
	Temperature						
(22) Operation environment		Performance guaranteed: 0°C~+40°C					
	Humidity	RH 20~80% with no condensation					
(00) (1	Temperature	-25°C ∼ +60°C					
(23) Storage environment	Humidity	RH 20~80% with no condensation					
	omplim	entsofphas					

5.2. Camera Output Signal Specification

l.	tem	Specification				
(1) Video output data	Video Output	640 (H) × 480(V)) At Full Frame Scan Mode			
	LVAL output	LVDS	Camera Link connector			
	FVAL output	LVDS				
	DVAL output	LVDS				
(2) Sync. Signal I/O	SP(Exposure)	LVDS				
	HD output	LVTTL	6pins Circular connector			
	VD output	LVTTL				
	Exposure	LVTTL J				
	Polarity	POSI/NEGA Selectable				
	Min width of trigger pulse	10 μ s				
(2) Trigger input	Camera Link input	LVDS : CC1 input	Camera Link connector			
(3) Trigger input	TTL input	LVTTL: No.2 pin	6pins Circular connector			
			VIH Min. 2.0V			
			VIL Max. 0.8V			
(4) Serial	SerTC (Serial to Camera)	Camera Lin	k input (LVDS)			
Communication	SerTFG (Serial to Frame Gra	abber) Camera Link output (LVDS)				
	White Clip Level	Digital 8bit :FF				
(5) Video output signal	Setup Level	Digital 8bit .00	SH .			
	Dark Shading	Digital 8bit :under ±04h for both vertical and horizontal.				
		(condition: gain 0dB)				

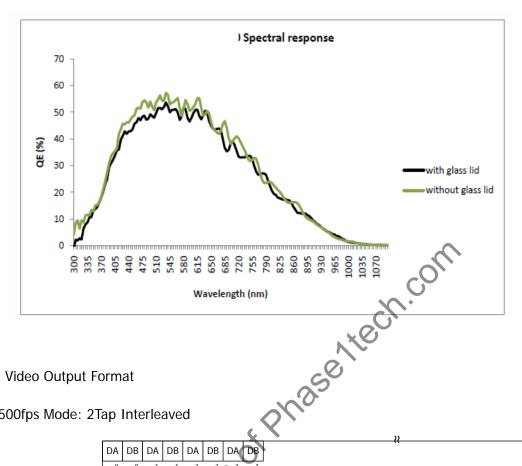
5 seconds shall be waited after turning on power to get proper camera operation.



6pins Circular Connector at rear: GPIO interface

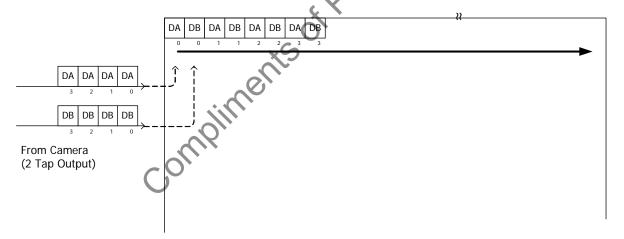
5.3. CMOS Spectral Response (Representative value)

XLens characteristics and illuminant characteristics are not considered.



Video Output Format 5.4.

VGA 500fps Mode: 2Tap Interleaved



5.5. Camera Link Port Data Bit Assignment (Base Configuration)

Port/bit	At 8bit output setting	At 10bit output setting
Port A0	DA:bit0[LSB]	DA:bit0[LSB]
Port A1	DA:bit1	DA:bit1
Port A2	DA:bit2	DA:bit2
Port A3	DA:bit3	DA:bit3
Port A4	DA:bit4	DA:bit4
Port A5	DA:bit5	DA:bit5
Port A6	DA:bit6	DA:bit6
Port A7	DA:bit7[MSB]	DA:bit7
Port B0	DB: bit0[LSB]	DA:bit8
Port B1	DB: bit1	DA:bit9[MSB]
Port B2	DB:bit2	Not in use
Port B3	DB:bit3	Not in use
Port B4	DB:bit4	DB:bit8
Port B5	DB:bit5	DB:bit9[MSB]
Port B6	DB:bit6	Not in use
Port B7	DB:bit7[MSB]	Not in use
Port C0	Not in use	DB:bit0[LSB]
Port C1	Not in use	DB:bit1
Port C2	Not in use	DB:bit2
Port C3	Not in use	DB:bit3
Port C4	Not in use	DB:bit4
Port C5	Not in use	DB:bit5
Port C6	Not in use	DB:bit6
Port C7	Not in use	DB:bit7

6. Function Settings

Camera functions can be set with serial data communications.

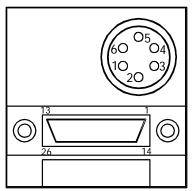
Function	Address	Data
		0: 0 dB
		1: +6 dB
Gain	001	2: + 12 dB
		3: Manual Gain (Refer to address 008.)
		4~255: 0dB
		0: 1/500s
		1: 1/500s
		2: 1/750s
		3: 1/1000s
		4: 1/1500s
		5: 1/2000s
Shutter		6: 1/2500s
(at full frame scan mode)		7: 1/4000s
		8: 1/5000s
※For partial scan mode,	002	9: 1/10000s
please refer to Section 9.		10: 1/15000s
		11: 1/20000s
		12: 1/25000s
		13: 1/30000s
		14: 1/40000s
		15: 1/50000\$
		16: Manual Shutter (Refer to address 009&010.)
		17~255; 1/500s
		0: Normal Shutter Mode (Trigger Shutter Mode OFF)
		1. Fixed Trigger Shutter Mode
Tringer Charter Made	004	(Shutter speed can be set with address 002.)
Trigger Shutter Mode	004	2: Pulse Width Trigger Shutter Mode
	21,	(Shutter speed can be set with trigger pulse width.)
		3~255: Normal Shutter Mode (Trigger Shutter Mode OFF)
		0: Full Frame Scan Mode
Scan Mode	005	1: Partial Scan Mode (Vertical 1/2)
Scarr wode	003	2: Manual Partial Scan Mode (Refer to address 016/017 & 019/020.)
		3~255: Full Frame Scan Mode
Manual Gain Control	000	0~120: 0~+12dB 0.1dB/step **Set the data of address 001 to 003.
	800	121~255: +12dB
		0~480: 1/50000s~1/500s
		481~2047: 480
		X The setting will be 1 line when 0 is set.
		Exposure Time = The set value × 1line Time [s]
 Manual Shutter Control	009&010	1line Time [s] = ((output pixels/2tap)+5) × 1/79.99MHz
3	2272313	At full frame scan, output pixels = 480
		1line Time \doteq 4.06 μ s
		WALL 000 LL L III 04/
		**Address 002 data shall be 016.
		Address 009 MSB and Address 010 LSB make 11bit in total.

Function	Address	Data				
		0: Positive Input				
Trigger Polarity	011	1: Negative Input				
	0: Positive Input 1: Negative Input 2~255: Positive Input 2~255: Positive Input 2~255: Positive Input 0: Camera Link Connector 12226-1100-00 PL L 1: 6pins Circular Connector 12226-1100-00 PL 0: 8bit output data 2~255: Camera Link Connector: 12226-1100-00 PL 0: 8bit output data 2~255: Bit output data 2 × 255: Bit output					
		0: Camera Link Connector 12226-1100-00 PL	LVDS			
Input Trigger Port Selection	012	1: 6pins Circular Connector	TTL			
	O: Positive Input 1: Negative Input 2~255: Positive Input 2~255: Positive Input 2~255: Positive Input 0: Camera Link Connector 12226-1100-00 PL LVI 1: 6pins Circular Connector 12226-1100-00 PL LVI LVI 1: 6pins Circular Connector 12226-1100-00 PL LVI					
		0: 8bit output data				
Output Data Selection	013	1: 10bit output data				
1						
		0~Max. Value ※ 1line/step				
Vertical Partial Coop		**Max. value shall be limited according to the formula below.				
	016&017	480 (Vertical Partial Scan output max. lines – Vertical Partial Scan	output lines)			
Trigger Polarity 0: Positive Input 1: Negative Input 2~255: Positive Input 0: Camera Link Connector 1222 1: 6pins Circular Connector 2~255: Camera Link Connector 2~255: Camera Link Connector 2~255: Camera Link Connector 2~255: Bit output data 1: 10bit output data 2~255: 8bit output data 2~255: 8bit output data 0~Max. Value ※ 1line/step ※Max. value shall be limited accor 480 (Vertical Partial Scan output m ※Address 016 MSB and Address 017 0~480: 1line/step Min.:1li 481~2047: 480 Vertical Partial Scan Output Lines Vertical Partial Scan Output Lines Remote Communication Baud Rate Setting 0: Positive Input 1: Negative Input 0: Camera Link Connector 1222 1: 6pins Circular Connector 2~255: Camera Link Connector 2~255: Bbit output data 0~Max. Value ※ 1line/step ※Max. value shall be limited accor 480 (Vertical Partial Scan output m ※Address 016 MSB and Address 017 0~480: 1line/step Min.:1li 481~2047: 480 0: 9600bps 1: 19200bps 2: 38400bps 3: 57600bps 4: 115200bps 5~255: 9600bps Data Save 032 Input 083 to save address 000 ~		**Address 005 data shalla be 002.				
	Address 016 MSB and Address 017 LSB make 1 bit in total.					
		0~480: 1line/step Min.:1line/Max:480 lines				
Vantical Dantial Cook		481~2047: 480				
Input Trigger Port Selection Output Data Selection Vertical Partial Scan Start Position Vertical Partial Scan Output Lines Remote Communication Baud Rate Setting Data Save	019&020	1 line shall be set when 0 is set.				
		Address 019 MSB and Address 020 LSB make 11bit in total.				
		*Address 005 data shalla be 002.				
		0: 9600bps				
		1: 19200bps				
Remote Communication	020	2: 38400bps				
Baud Rate Setting	030	3: 57600bps				
		4: 115200bps				
		5~255: 9600bps				
Data Save	032	Input 083 to save address 000 ~ 031 to EEP-ROM.				
		Input 083 to save address 000 ~ 031 to EEP-ROM.				

7. External Connector Pin Assignment

7.1. 6pins Circular Connector HR10-7R-6PA (HIROSE) equivalent

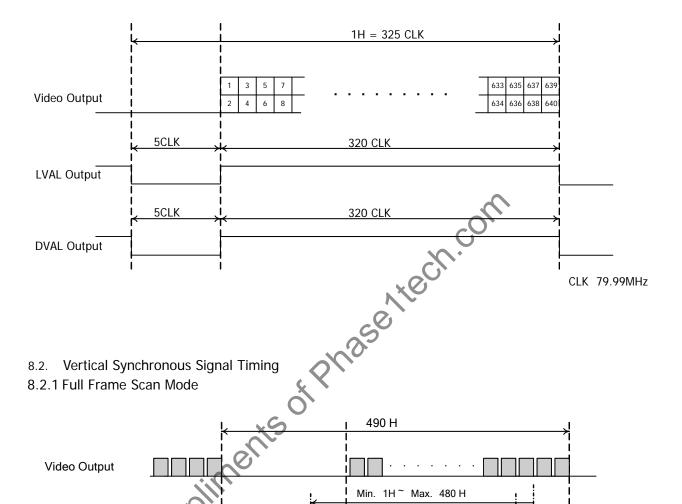
Pin No.	
1	Power IN DC+12V
2	Trigger IN(TTL level)
3	HD
4	VD
5	Exposure
6	GND



7.2. 26pins Mini Camera Link Connector 12226-1100-00 PL (SUMITOMO 3M)

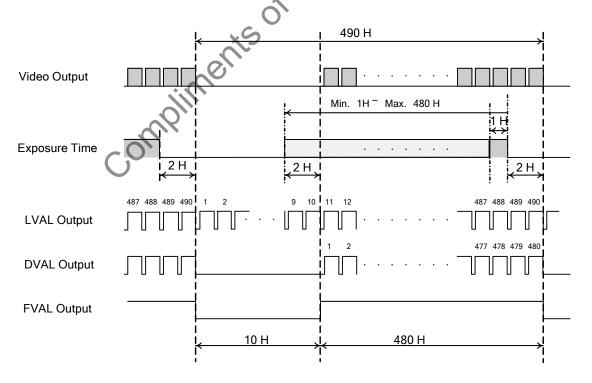
Pin No.		Pin No.	1/6
1	GND	14	GND
2	X0-	15	X0+
3	X1-	16	XT+
4	X2-	17	X2+
5	Xclk-	18	Xclk+
6	Х3-	. 19	X3+
7	SerTC+	20	SerTC-
8	SerTFG-	21	SerTFG+
9	CC1- (Trigger IN-)	22	CC1+ (Trigger IN+)
10	CC2+	23	CC2-
11	CC3-	24	CC3+
12	CC4	25	CC4-
13	GND	26	GND

- **Timing Chart**
- 8.1. Horizontal Synchronous Signal Timing



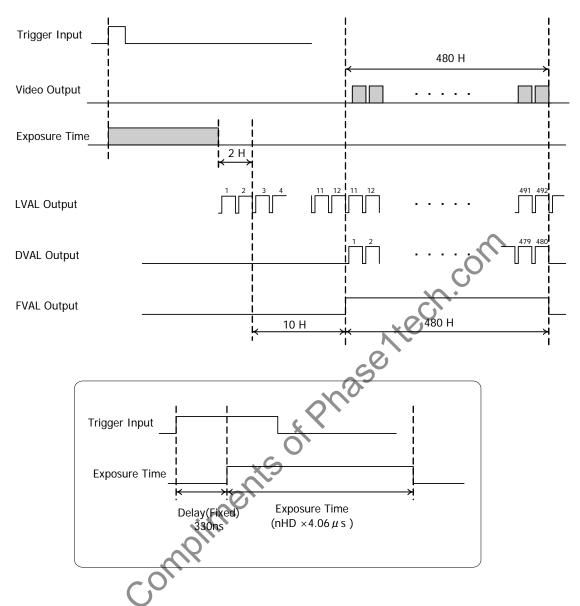
8.2. Vertical Synchronous Signal Timing

8.2.1 Full Frame Scan Mode



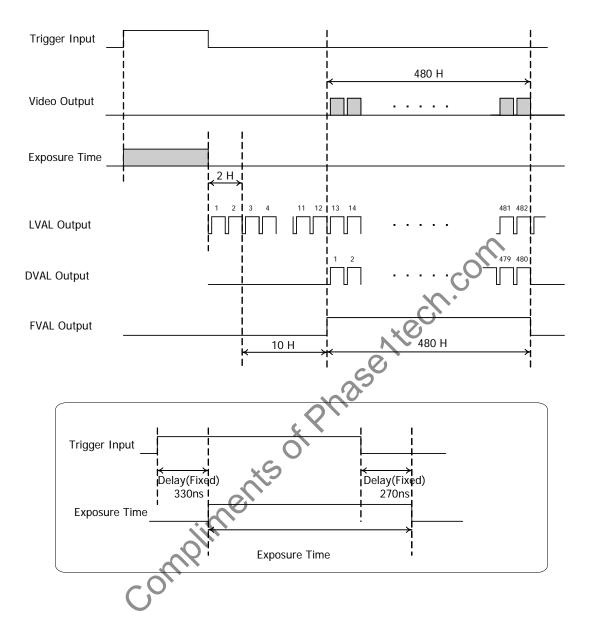
XVideo output signal delays by 2H from Exposure Time.

8.2.2 Fixed Trigger Shutter Mode



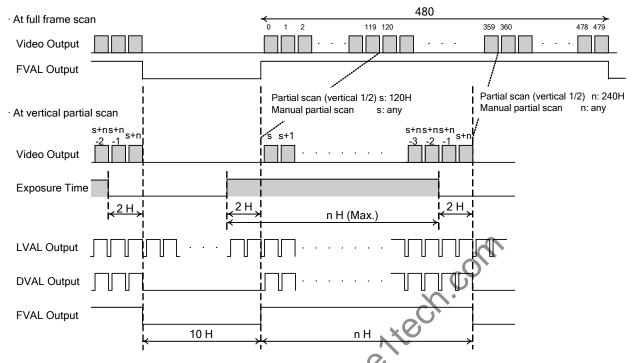
XVideo output signal delays by 2H from Exposure Time.

8.2.3 Pulse Width Trigger Shutter Mode



XVideo output signal delays by 2H from Exposure Time.

- 9. Partial Scan Mode
 - Vertical Partial Scan



- s: Vertical partial scan starting position (address 016&017)
- n: Vertical partial scan output lines (address 019 & 020)

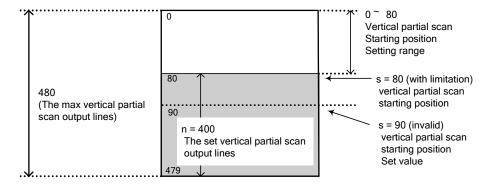
Scan Mode (address:005)	S	n	Vertical Sync. Frequency (Hz)
0:Full frame scan mode	0	480 💃	502.29
1:Partial scan mode (Vertical 1/2)	120	240	984.49
2:Manual partial scan mode	Any	any	79.99MHz /((Vertical partial scan output lines +10)×(325))

•The max value of vertical partial scan starting position is limited with the formula below since vertical partial scan output line has priority.

The max value of vertical partial scan starting position

- =480(The max value of vertical partial scan output line) Vertical partial scan output lines
- (Ex.) When 400 is set as vertical partial scan output lines, the max value of vertical partial scan starting position will be 480-400 = 80.

If vertical partial scan starting position is set to 90 with this time, vertical partial scan output line has priority so that vertical partial scan starting position shall be limited to 80.



* At manual partial scan mode, manual shutter value to be set shall meet the following conditions.

The set manual shutter lines \leq Vertical partial scan output lines

If the condition above is not met, shutter lines to be set will be the same number as vertical partial scan output lines.

10. Remote Interface Function

Camera can be controlled by external computers and others via camera link interface.

(1) The settings for RS-232C are as follows.

Baud Rate : 9600bps,19200bps,38400bps,57600bps,115200bps

Data : 8bit Stop bit : 1bit Parity : None

XON/XOFF : not controlled

(2) Control code

• The total control code is 14 bits, which conforms to ASCII code.

 The control code consists of camera No. process code, remote controller address, remote controller data, and CR. Execute Read/Write through PC, and the camera will reply the data.

1	2	3	4	5	6	7byte目	8	8 9 1		- (1)1	12	13	14
	Camera No.				Process code		Rei	mote	Remote controller			CR	
				controller			data						
						add	dress						
000	000000: Common No.				"R" Read mode	Ple	ease	refer to	000~	255			
				"W" Write mode	the address						0Dh		
Ded	Dedicated Camera No.			"C"Camera	tal	ble of	f 6.						
!		mode	Fu	ınctio	n								
						ζ×	se	tting.					

Camera No

Please send the common code, "000000", consist of 6 bytes of characters/numeric strings.

The returned data from the camera shall be the dedicated camera No assinged for that specific camera.

Process code

Input any one of R, W, or C to the process code.

R (read mode) is to read the data of remote controller address.

Please be noted to set any dummy data (000 \sim 255) to 11th \sim 13th, since a command shall consists of 14 bytes.

W (write mode) is to write the data to the remote controller address.

Please be noted that the data cannot be saved into EEPROM of the camera.

(Reboot the camera, and the data is reset to the initial setting.)

To save the data into EEPROM, please refer to Clause 5. Function Setting.

Note: Once the data was saved into EEPROM, it may not be reset to t he initial settings.

C is the code to send the data back from the camera.

Note: Do not set code C when sending the data from PC side.

Remote controller address

Note: Do not save the data into the address other than specified, since it may cause the damages or malfunction of the camera.

Remote controller data

Set the decimal number ($000\sim255$) for the remote controller data. Please be noted to set any dummy data at read mode.

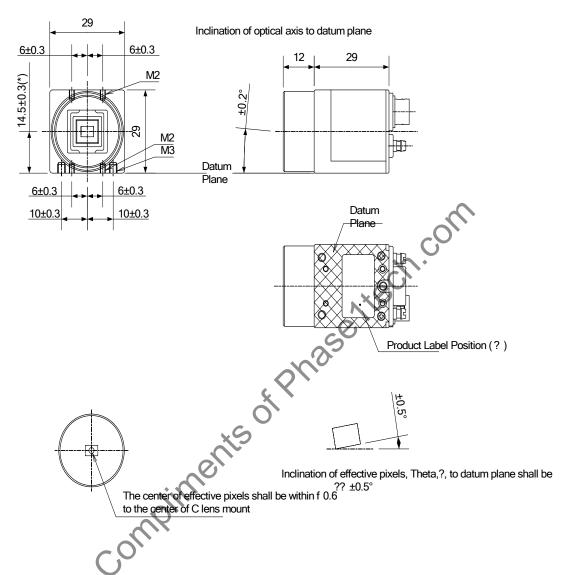
CR

Be sure to input "CR" to confirm the end of the command.

11. Initial Settings

Function	Address	Data
Gain	001	0: 0dB
Shutter	002	0: 1/500s
Trigger Mode	004	0: Normal Shutter Mode (Trigger Shutter Mode OFF)
Scan Mode	005	0: Full Frame Scan Mode
Manual Gain Control	800	0: 0dB
Manual Shutter Control	009&010	480, 1/500s
Trigger Polarity	011	0: Positive Input
Input Trigger Port Selection	012	0: Camera Link connector (12226-1100-00 PL)
Output Data Selection	013	0: 8bit Output Data
Baud Rate	030	0:9600bps

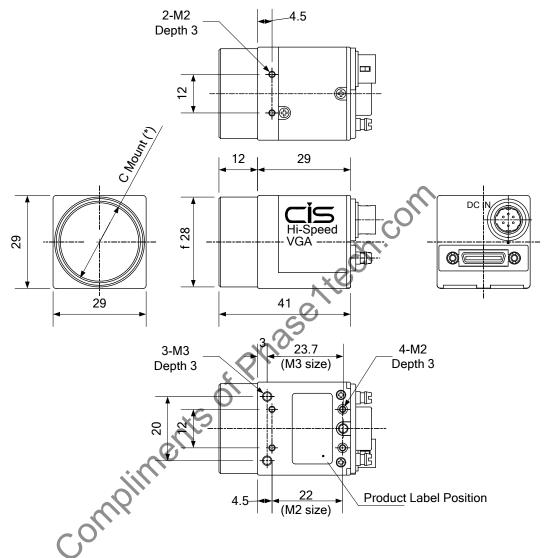
12. CMOS Optical Axis Accuracy



(*) Dimensions from datum plane to the center of the lens mount

910-006-01-01 (Unit:mm)

13. Dimensions



*2)C mount screws comply with ANSI/ASME B1.1, 1-32UN(2B).

*1)Screw length from the lens mount surface shall be under 6mm.

And protruding portion shall be less than 10mm.

999-547-00-00 (Unit:mm)

14. Cases for Indemnity (Limited Warranty)

We shall be exempted from taking responsibility and held harmless for damage or losses incurred by the user in the following cases.

- In case damage or losses are caused by fire, earthquake, or other acts of God, acts by third party, deliberate or accidental misuse by the user, or use under extreme operating conditions.
- In case indirect, additional, consequential damages (loss of business interests, suspension of business activities) are incurred as result of malfunction or non-function of the equipment, we shall be exempted from responsibility for such damages.
- ♦ In case damage or losses are caused by failure to observe the information contained in the instructions in this product specification & operation manual.
- ♦ In case damage or losses are caused by use contrary to the instructions in this product specification & operation manual.
- ♦ In case damage or losses are caused by malfunction or other problems resulting from use of equipment or software that is not specified.
- ❖ In case damage or losses are caused by repair or modification conducted by the customer or any unauthorized third party (such as an unauthorized service representative).
- ♦ Expenses we bear on this product shall be limited to the individual price of the product.

15. Sensor Pixel Defect

Sensor pixel defects might be noted with time of usage of the products.

Cause of the Sensor pixel defects is the characteristic phenomenon of CMOS itself and CIS is exempted from taking any responsibilities for them.

16. Product Support

When defects or malfunction of our products occur, and if you would like us to investigate on the cause and repair, please contact your distributors you purchased from to consult and coordinate.

Camera control sample software (RS232C) is downloadable from our web but we shall be exempted from taking responsibility and held harmless for damage or malfunction of your hardware and software caused by using this control software. The purpose of the control software prepared is for you to check operation and evaluate our products. Please be noted that CIS does not customize the program nor provide source code.