

# **PL-D795**

# CMOS | SONY IMX264 | GLOBAL SHUTTER

The PL-D family of cameras links together the benefits of high frame rate CMOS technology with the high speed data throughput of USB 3.0 technology. The PL-D795 camera provides low noise images for outstanding value for a broad range of industrial applications.



## **KEY FEATURES**





FRAMES



















### TYPICAL APPLICATIONS

Parts inspection Strength Testing Metrology

**Biometrics** 

**Medical Imaging** 

PCB & Flat Panel Display Inpsection



PL-D795

### **TECHNICAL SPECIFICATIONS**

#### **SENSOR**

Sensor Sony IMX264
Type CMOS Global Shutter
Resolution 5.01MP (2448 x 2048)
Pixel Pitch 3.45 µm x 3.45 µm
Active Area 11.1 mm diagonal

#### **PERFORMANCE SPECIFICATIONS**

FPN < 0.03% of signal
PRNU < 0.4% of signal
Dynamic Range 70 dB
Bit Depth 12-bit
Color Data Formats Bayer 12 Packed, Bayer 16 & YUV422
Mono Data Formats Mono 8, Mono 12 Packed & Mono 16

#### FRAME RATES

 Resolution
 Free Running

 2448 x 2048
 35.7 fps

 1280 x 1024
 70.2 fps

 640 x 480
 143.9 fps

Frame rates will vary based on host system and configuration \*Above calculations based on fixed frame rate mode

#### **INTERFACES**

Interface | Date rate USB 3.0 | Micro-B | 5Gbps Board Level Trigger 8-pin Molex 1.25mm pitch Connector **Enclosed Trigger** Hirose round 8-pin Connector Software and hardware Trigger **Board Level Trigger** 1 input, 3.3V (with internal Input pullup resistor) **Enclosed Trigger Input** 1 optically Isolated, 5-12V DC at 4-11 mA Board Level GPO/Strobe 2 outputs, 3.3V **Enclosed GPO/Strobe** 2 outputs, 3.3V and 1 optically isolated max 40V DC, max 15mA GPI 1 input, 3.3V (with internal

#### MECHANICALS

Dimensions (mm) 55 x 38.5 x 30.29
Weight (g) 35.8 (Board level without optics)
Mounting C-Mount

pullup resistor)

#### **POWER REQUIREMENTS**

Voltage Required 5V DC (from USB connector)

#### **PIN NAME & FUNCTION**

- 1 3.3V power output
- 2 TRIGGER/GPI 3.3V HCMOS input
- 3 Ground
- 4 GPO1, 3.3V HCMOS output
- 5 GPO2, 3.3V HCMOS output
- 6 Clock, 3.3V (I2C access for OEMs)
- 7 Data, 3.3V (I2C access for OEMs)
- 8 No connection

Board connector: Molex (8-pin, 1.25mm pitch, vertical); Cable receptacle: Molex 51021-0800; Cable crimp terminals: Molex 50079-8100

#### **ENCLOSED GPIO INTERFACE PIN OUTPUT DESCRIPTION**

- 1 VBUS (Power output from USB3 cable)
- 2 TRIGGER + (optically isolated)
- 3 TRIGGER (optically isolated)
- 4 GPO1 + (optically isolated)
- 5 GPO1 (optically isolated)
- 6 GPO1, 3.3V HCMOS output (I2C SCL for autofocus)
- 7 GPO2, 3.3V HCMOS output (I2C SDA for autofocus)
  - Ground (logic and chassis ground)

#### **ENVIRONMENTAL & REGULATORY**

Compliance FCC, CE & RoHS
Shock & Vibration 300 G & 20 G (10Hz - 2KHz)
Operating Temperature 0°C to 50°C
Storage Temperature -45°C to 85°C

#### **SOFTWARE**

Pixelink Capture Control & operate multi-camera
Pixelink SDK Software Development Kit
Pixelink µScope Acquisition, analysis & reporting
3rd. Party U3V Vision Applications

Linux x86

Linux

Linux

#### **COMPUTER & OPERATING SYSTEM**

Windows

|  |                     |                       |                                  | ArmV7                 | ArmV8                 |
|--|---------------------|-----------------------|----------------------------------|-----------------------|-----------------------|
|  | Processor           | Intel i5 or<br>better | Intel i5 or<br>better            | Arm7<br>(32 bit)      | Arm8<br>(64 bit)      |
|  | Memory              | 4GB recommended       | 4GB recommended                  | 2GB                   | 2GB                   |
|  | Hard Drive<br>Space | 150 MB                | 150 MB                           | 50 MB                 | 50 MB                 |
|  | Operating<br>System | Windows<br>7/8/10     | Ubuntu<br>14.04/16.04<br>Desktop | Ubuntu<br>14.04/16.04 | Ubuntu<br>14.04/16.04 |

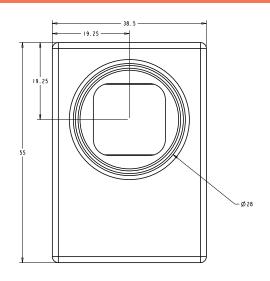


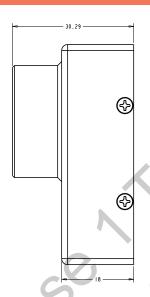


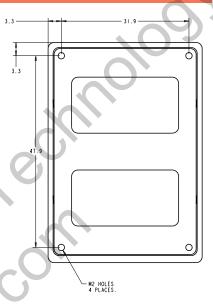
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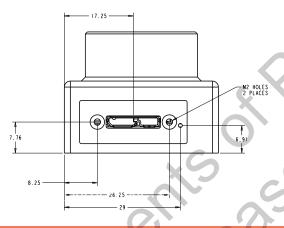
## MECHANICAL DRAWINGS & RESPONSIVITY CURVES

#### MECHANICAL DRAWINGS

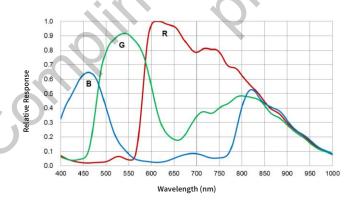




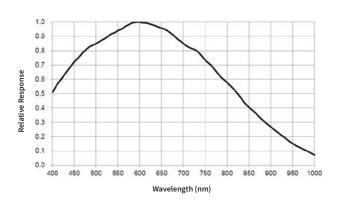




#### **RESPONSIVITY CURVE - COLOR**



#### **RESPONSIVITY CURVE - MONO**





PI-D795

### PIXELINK'S INDUSTRY LEADING SOFTWARE

#### PIXELINK CAPTURE

**Pixelink Capture** is powerful multi-camera software application designed to configure "n" numbers of cameras and stream "n" number of cameras simultaneously in real-time high-quality video viewed in a multi-window environment. Pixelink Capture offers options for complex image enhancements such as; exposure control, filtering, frame-by-frame property changes in addition to multi-camera application testing and configuration.

Pixelink Capture also provides features to measure supporting; point, line, circle, rectangle, polyline and polygon measurements while determining pixel location. After creating spatial calibration, the user can then review and adjust before exporting the findings to an Excel spreadsheet for further analysis. Pixelink Capture also has integrated lens control (zoom & focus) for Navitar motorized lenses and accurate autofocus options for Navitar motorized fine focus mechanisms.

Visit pixelink.com for more detailed information.

#### PIXELINK SDK

Providing full control of all camera functions, the **Pixelink Software Developers Kit (SDK)** is the software package of choice for developers and system integrators who are integrating Pixelink cameras into their applications. The Pixelink SDK provides access to the full Pixelink Application Programming Interface (API) and provides sample applications, wrappers for many 3rd party controls, such as LabVIEW, along with full documentation.

The Pixelink SDK is compatible with Microsoft Windows and popular Linux platforms. When using the Pixelink SDK, developers can integrate Pixelink cameras into their custom applications with ease.

Visit pixelink.com for more detailed information.

### **AVAILABLE CONFIGURATIONS**

PL-D795CU PL-D795CU-BL PL-D795CU-T PL-D795MU PL-D795MU-BL PL-D795MU-T

Color Space C = Color M = Mono NIR = Near Infrared Interface F = Firewire G = GigE U = USB

Housing
CS = CS Mount
S-BL = S Mount Board Level
BL = Board Level
T = Trigger

